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Scientific machine learning for fluid flow modeling and design

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Overview

- A very brief introduction to Fluid Mechanics
- Scientific machine learning in Fluid Mechanics
	- Requirements, challenges and opportunities
	- Examples
	- Toward more generalizable data-driven models
- Conclusions and outlook

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Fluid Mechanics

- **Fluids play a fundamental role for life**
	- Human body contains 60% water
	- 2/3 earth's surface covered by water
	- Atmosphere extends for 17km above earth's surface
- Fluid mechanics is part of our history
	- Geomorphology
	- Human migrations and birth of civilizations
	- Modern scientific and mathematical theories
- Key to many problems in science and engineering
	- Turbulence, geosciences, biology, astrophysics
	- Weather and climate
	- Aerospace, Energy, Industrial processes, health

Fluid mechanics is in almost every daily event

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Investigating fluids

1. Experimental Fluid Mechanics

Archimede (C. 287-212 AC)

Galileo (C. 287-212 AC) Reynolds (1842-1912)

- 2. Theoretical Fluid Mechanics
- 3. Computational Fluid Dynamics
- 4. High-Performance computing
- **5. Data-driven Fluid Mechanics**?

Euler (1707-1783) (1667-1748) (1785-1836) Bernoulli

Navier

Stokes (1819-1903) (1875-1953) Prandtl

Taylor (1886-1975)

Von Neumann (1903-1957) Harlow (1928-2016)

Governing equations (continuum limit)

- Conservation of mass : $\frac{D\rho}{D}$ Dt $= -\rho \nabla \cdot \mathbf{v}$
- **Conservation of momentum :** $\rho \frac{Dv}{dt}$ $\frac{\partial v}{\partial t} = -\nabla p + \nabla \cdot \tau_v + \rho f$
- **Conservation of energy** : $\rho \frac{DE}{Dt}$ $\frac{\partial E}{\partial t} = -\nabla \cdot (p\mathbf{v}) + \nabla \cdot (\mathbf{v} \cdot \mathbf{\tau}_v) + \rho \mathbf{f} \cdot \mathbf{v} - \nabla \cdot \mathbf{q}$
- Constitutive equations :
	- Rheology models : e.g. Newtonian fluid $\tau_{\rm v} = 2 \mu {\bf S} + \lambda tr({\bf S}) I$
	- Heat flux : $\mathbf{q} = -\kappa \nabla T$
	- Equation of state, $p = p(\rho, e)$

Multi-fluid equations…

■ Mass, momentum (and energy) conservation for each fluid k

$$
\frac{\partial(\rho_k \alpha_k)}{\partial t} + \nabla \cdot (\rho_k \alpha_k \mathbf{v}) = \alpha_k M_k
$$

$$
\frac{\partial(\rho_k \alpha_k \mathbf{v}_k)}{\partial t} + \nabla \cdot (\rho_k \alpha_k \mathbf{v}_k \mathbf{v}_k)
$$

= $-\alpha_k \nabla p + \nabla \cdot (\alpha_k \mathbf{t}_v) + \rho_k \alpha_k \mathbf{f} + \mathbf{I}_k$

$$
\frac{\partial(\rho_k \alpha_k T_k)}{\partial t} + \nabla \cdot (\rho_k \alpha_k \mathbf{v}_k T_k)
$$

= $W_{p,k} + W_{\tau,k} + W_{f,k} + W_{I,k} + \dot{Q}_k$

■ Supplementary models for:

 (d)

• Rheology, thermophysical properties, mass- echange terms, interfacial forces, heat fluxes…

 (b) _{Narcy&Colin 2015} (c)

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The "simple" case

■ Navier-Stokes equations for a single-phase, single-species, incompressible, constant-property Newtonian fluid :

$$
\frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v} = -\frac{1}{\rho} \nabla p + \nu \nabla^2 \mathbf{v}
$$

 $\nabla \cdot \mathbf{v} = 0$

■ Buckingham theorem \rightarrow nondimensional form

 $\nabla \cdot \mathbf{v} = 0$ ∂ v $\frac{\partial}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v} = -\nabla p +$ 1 $\frac{1}{\text{Re}} \nabla^2 \mathbf{v}$

- Reynolds number : $Re =$ V_{ref} Lref $\overline{\nu}$
	- Ratio of inertia to viscous forces \Leftrightarrow ratio of diffusion to convection time scales
	- Ratio of nonlinear to linear terms!

 $Re = 0.16$ $Re = 26$ $Re = I$

 $Re = 2000$

Van Dyke, 1982 8

Laminar flow

Turbulent flow

Re

Multiples scales

https://svs.gsfc.nasa.gov/3820

Challenges

- Analytical solutions possible for a limited range of simple flow cases
- Asymptotic expansions, linearization techniques...
	- Simplifying assumptions
	- But **parcimonious and interpretable** models! Generalizable to some extent…

Challenges

- § Experimental investigation costly and time consuming
- § Incomplete/noisy (inaccessible regions, scale cutoff, reconstruction errors, unobservable quantities)
- § One-shot! Interpretable? Uncertainties?

Smits&Hultmark, 2014 and particle-tracking/innersolved-substitute of the contract of the contr s/fluid-mechanics/time-resolved-3dparticle-tracking/i

Time-resolved tomographic PIV of incompressible flow past a cylinder at ReD=27000 (Scarano et al., 2022)

Challenges

Solving all scales generally unfeasible à **coarse-grained approaches**

§ **DNS**

- Number of cells required for solving all scales $\approx \left(\frac{L}{m}\right)$ η $B^3 = Re^{9/4}$
- Cost≈ $Re^{11/4}$ (number of cells x number of time iterations)

§ **Large Eddy Simulation**

- Free-shear flow: $\approx Re^{0,4}$; cost $\approx Re^{0,5}$
- Wall-bounded flows (Wall-Resolved LES, WRLES) : $\approx Re^{1,8}$; cost $\approx Re^{2,4}$
- à **quasi-DNS resolution**

§ **RANS**

- Drastic reduction of computation time
- Models are less universal and suffer from **uncertainties**

Multiple modeling fidelities

§ **High carbon footprint of large simulations**

- Hi-Fi CFD (DNS, Wall-Resolved LES) limited to low/moderate-Reynolds numbers
- Mid-Fi CFD Wall-Modelled LES, WMLES, and hybrid RANS/LES are attractive alternatives but do not solve all of the problems

DNS [Yang et al., 2024]

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- Scientific discovery
- Prediction and design
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The promises of Machine Learning

Potentially disruptive impact of artificial intelligence/**machine learning (ML)** techniques:

Abundant HiFi databases \rightarrow super-resolution, feature extraction, model augmentation, digital twins, control, surrogate modeling, clustering, classification…

Can ML enable fast HiFi-quality for scientific discovery and engineering?

Requirements

- Interpretable and generalizable models
	- As simple as possible, but not simpler (parcimony principle)

o Example

$$
\nabla^2 \phi = 0, \frac{\partial \phi}{\partial n} = 0 \quad \text{and} \quad \frac{p}{\rho} + \frac{1}{2} |\nabla \phi|^2 = cte
$$

- Uncertainty control
	- Tell something about model reliability, especially in unseen environments
- Deal with sparse/noisy data
	- Very partial sampling from some unknown distribution

Application 1: Reduced-order/surrogate models/neural operators

- The response of a costly model to some parameters is reproduced by a cheap ML model (surrogate model or metamodel)
	- Inclusion of physical constraints in the loss function
- Useful for optimization, uncertainty quantification, parameter estimation, control tasks
- § Surrogate quality control?
- § Amount of required data vs range of configurations potentially covered?

Catalani et al., 2024, Multiscale Implicit Neural Representation (INR)

Application 1: Reduced-order/surrogate models/neural operators

- § Nonlinear reduction of flow dynamics, pattern extraction, causality effects
- § Single flow, spectral bias (small structures ill-captured)

Fukami et al. 2023

Application 1: Replace costly simulators

- **EXEQUARE:** Neural operators learn the solution operator
- FourCastNet (NVIDIA), short for Fourier ForeCasting Neural Network
- Global data-driven weather forecasting model
- Accurate short to medium-range global predictions at 0.25◦ resolution.
- Dramatic reduction of CPU cost
- § Ensemble forecasting

Application 2: Flow control

- Drag reduction via Deep Reinforcement Learning
- **Discovery of new control strategies**
- Detection of sensitive flow structures

Guastoni et al., 2022

Application 3: Discovery/augmentation of models

■ Learn data-driven coarse-grained models

 $\lceil X_1 \rceil$

 X_2

… X_{Λ}

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3

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■ Symbolic regression, neural networks, random forests, Gaussian processes, …

Features X_2 $\qquad \qquad X_3$ Data

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DAM

High-fidelity CFD

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Open-box ML for the discovery of turbulence models

[Schmelzer et al., 2020]

SpaRTA = Sparse Regression of Turbulent-stress Anisotropy

■ Start with linear eddy viscosity model (here, Menter's $k - \omega$ SST)

$$
\tau_{ij}=2k\left(b_{ij}+\frac{1}{3}\delta_{ij}\right);~~b_{ij}=-\frac{\nu_t}{k}S_{ij};~~\nu_t=f(k,\omega)
$$

+ transport equations for k and ω

Internal additive corrections of Reynolds stress anisotropy (b_{ij}^A **) and turbulent transport equations (R):**

$$
b_{ij} = -\frac{v_t}{k} S_{ij} + b_{ij}^{\Delta} \qquad \frac{Dk}{Dt} = P + P^{\Delta} + D + T + R \qquad \frac{D\omega}{Dt} = P_{\omega} + P_{\omega,\Delta} + P_{\omega,R} + D + T
$$

E Learn b_{ij}^{Δ} and R from high-fidelity data

SPARSE SYMBOLIC IDENTIFICATION

Open-box learning from a dictionary of explicit operators

Bayesian learning : SBL-SpaRTA [Cherroud et al., 2022]

■ Find $p(\Theta_{\Box}$, α, $\sigma^2|b_{ij}^{\Box})$ using the efficient Sparse Bayesian Learning (SBL) algorithm (Tipping 2001)

- Solves a generalized linear regression problem
- Recursively **select** features in C_p dictionary and infer parameter posteriors

SBL-SpaRTA : discovered models

§ Training data

SBL-SpaRTA

■ Curved backward-facing step flow at Re=13700

Generalization

■ Customized models may generate large errors when applied outside their application range

Quest for the "universal" model

- Some degree of generality needed
- Hand-set "zonal" models not acceptable for industry

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Towards more generalizable ML models

§ **Model Mixtures**

- Large data sets: combining models trained on subsets better than single model trained over all data
- Out of distribution predictions: uncertainty on which model (among those at hand) is better
- Generate hypermodels by combining component models

Mixture of Experts

Spatial model aggregation (XMA) of turbulence models [de Zordo et al., 2021]

- Consider a set of K competing models $\mathbf{M} = \{M_1, M_2, ..., M_K\}$
- « Hypermodel »: $M_{hyp}(\mathbf{x}, \mathbf{\theta}) = \sum_{k=1}^{K} w_k M_K(\mathbf{x}; \mathbf{\theta})$, with

$$
w_k = w_k(\mathbf{x}) = w_k(\eta(\mathbf{x}))
$$

• Regress $W_k(\eta(\mathbf{x})|\mathbf{Y})$ from data as a function of features \rightarrow Random Forests, Gaussian Processes, ANN...

- Features from Ling&Templeton (2015)
- Predict local model weights for a new case $w_k(\eta(x)|Y)$ and use them to aggregate individual model predictions
- Uncertainty estimates can be obtained by aggregating the **component variances**

$$
Var[M_{hyp}(\mathbf{x}, \boldsymbol{\theta})] = \sum_{k=1}^{K} w_k^2 Var[M_K(\mathbf{x}; \boldsymbol{\theta})]
$$

XMA : offline training

[Cherroud et al., 2023]

XMA Training Workflow

XMA prediction: model blending

Oulghelou et al., 2024: https://arxiv.org/abs/2410.14431

Intrusive X-MA Prediction Workflow

NASA Turbulence Modeling Testing Challenge

■ Application to Test Case 4 2DWMH: 2D NASA Wall-Mounted Hump Separated Flow Validation Case

Training from clustered data

- § Training flows contain several physical processes at once
	- Equilibrium BL, non-equilibrium BL, separation, wakes, corner flows, vortices, shocks…
	- Training algorithms tend to find a compromise among such processes
- Is it possible to find a better training strategy?
	- IDEA: Train by clusters, then aggregate

Leggett et al. ASME J Turbo, 2016

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Conclusions

- Artificial intelligence and physics are changing one another
	- Physical modeling , simulation, and experiments can successfully merge with ML to mine large datasets or to solve complex problems
	- ML can be analysed under the lens of physics/mathematics
- Fluid Mechanics complex multiscale and highly nonlinear flow problems are difficult and costly to represent with standard modeling technique and may hugely benefit from AI
- High standards of scientific discovery (interpretability, uncertainties, ...) call for more generalizable ML
	- Enforcement of hard constraints, inductive biases, novel definitions of loss functions…
- Massive amount of HF data are becoming available BUT
	- Mostly limited to "simple" configurations and low Reynolds numbers
	- A relatively small number of well-detailed configurations is available
	- Use of **experimental data** is essential for reaching more complex, high-Reynolds configurations
- Likely, we will NEVER have enough data to cover all possible fluid flow processes BUT

Outlook

- "Smart" training instead of "brute-force" training → **learn the "language of fluids"**
	- Identify and extract features and "building blocks" representative of dominant physical processes
	- Recursively encode and combine blocks for prediction based on **context**
	- Use uncertainty estimates to **update** the model
- **Foundation models:** train from heterogeneous data and for multiple tasks, fine-tune
	- Translate into simpler, **explicit models** (AI-Feynman, pySR) for specific end use

Bommasani et al., 2022